

# Interpretability and Robustness for Multi-Hop QA

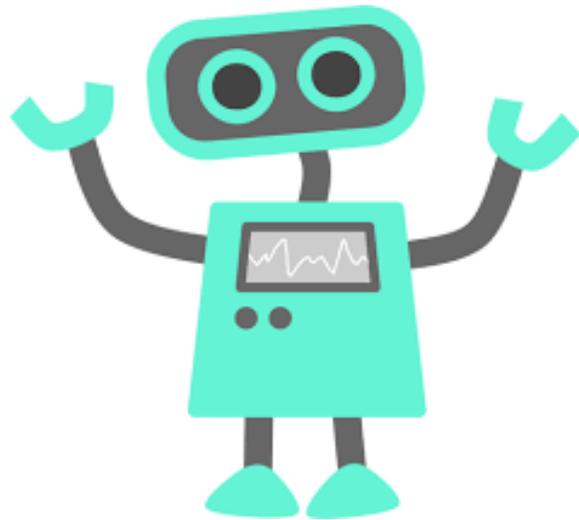
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THE UNIVERSITY  
*of* NORTH CAROLINA  
*at* CHAPEL HILL

(MRQA-EMNLP 2019 Workshop)

# Multihop-QA's Diverse Requirements



Interpretability and Modularity

Multiple Reasoning  
Chains Assembling

Adversarial Shortcut  
Robustness

Scalability and Data  
Augmentation

Commonsense/External  
Knowledge



- **Interpretability & Modularity for MultihopQA:**
  - Neural Modular Networks for MultihopQA
  - Reasoning Tree Prediction for MultihopQA
- **Robustness to Adversaries and Unseen Scenarios for QA/Dialogue:**
  - Adversarial Evaluation and Training to avoid Reasoning Shortcuts in MultihopQA
  - Robustness to Over-Sensitivity and Over-Stability Perturbations
  - Auto-Augment Adversary Generation
  - Robustness to Question Diversity via Question Generation based QA-Augmentation
  - Robustness to Missing Commonsense/External Knowledge
- Thoughts/Challenges/Future Work

# Interpretability and Modularity

## Question

“Which NFL team represented the AFC at Super Bowl 50?”

## Answer

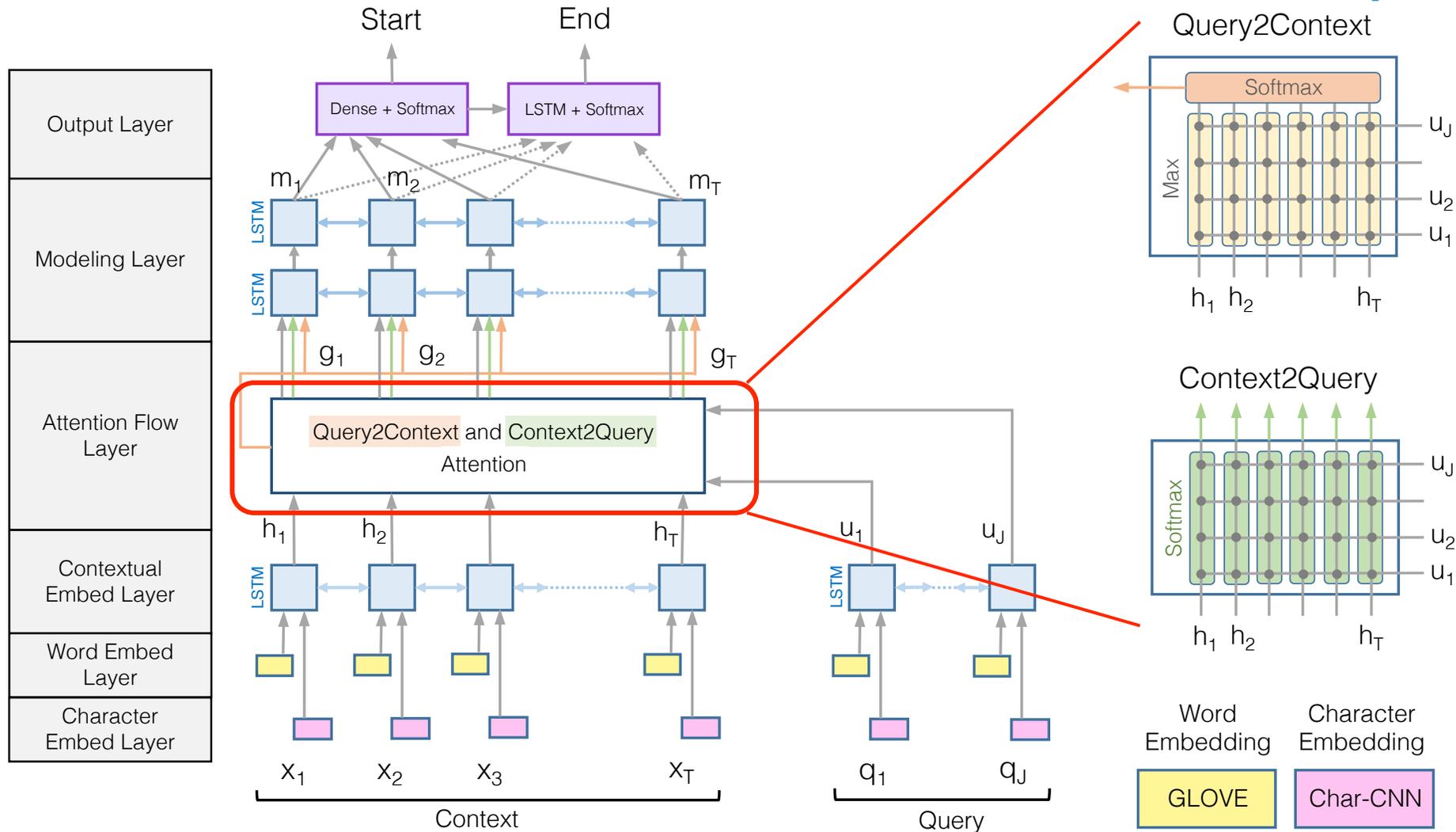
“Denver Broncos”

## Context

Super Bowl 50 was an American football game to determine the champion of the National Football League (NFL) for the 2015 season. The American Football Conference (AFC) champion Denver Broncos defeated the National Football Conference (NFC) champion Carolina Panthers ...

# Bi-directional Attention Flow Model (BiDAF)

[Seo et al., 2017]



# Multi-Hop QA: Bridge-Type

[Yang et al., 2018]

## Question

“What was the father of Kasper Schmeichel voted to be by the IFFHS in 1992?”

## Context

Kasper Schmeichel is a Danish professional footballer ... He is the son of former Manchester United and Danish international goalkeeper **Peter Schmeichel**.

**Peter Bolesław Schmeichel** is a Danish former professional footballer ... was voted the IFFHS World's Best Goalkeeper in 1992 ...



# Multi-Hop QA: Comparison-Type

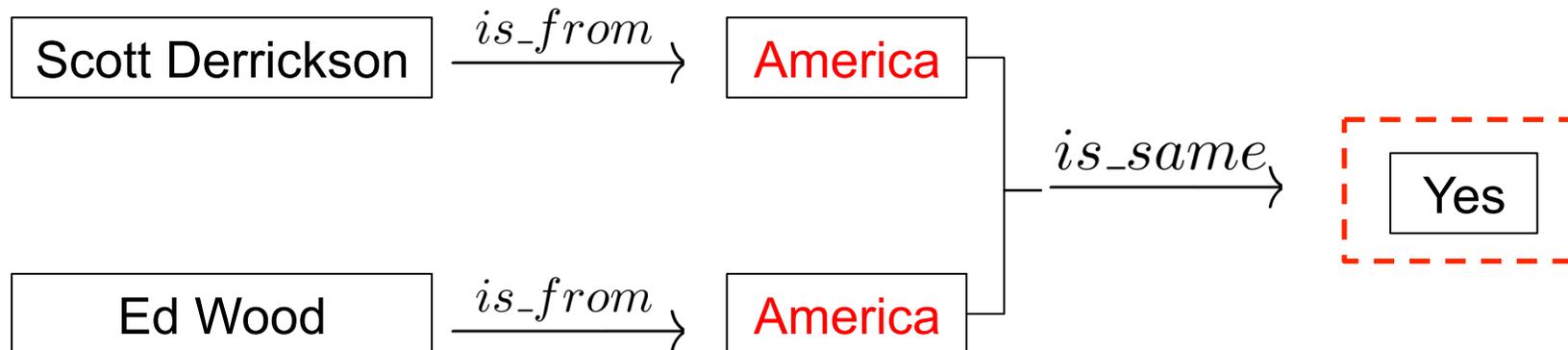
## Question

“Were Scott Derrickson and Ed Wood of the same nationality?”

## Context

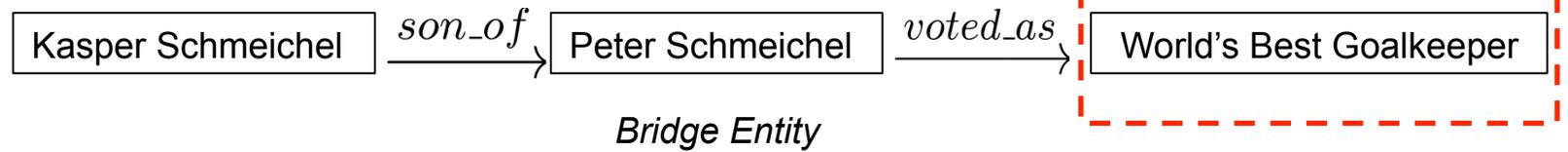
Scott Derrickson is an **American** director ...

Edward Wood Jr. was an **American** filmmaker ...

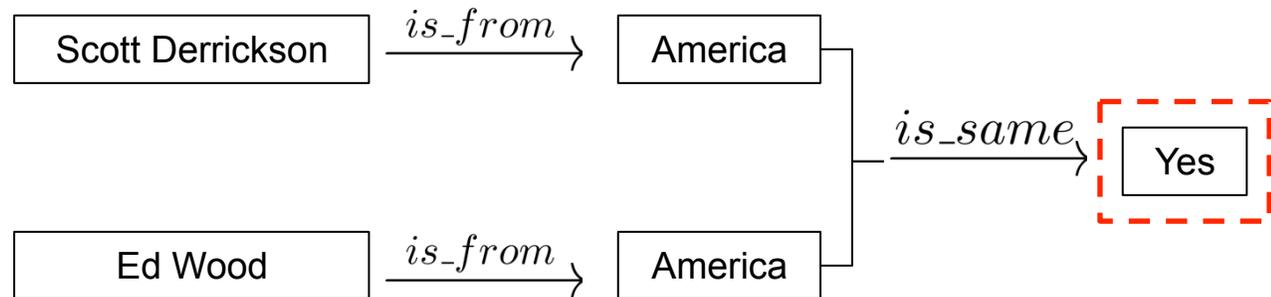


# Challenges: Different Reasoning Chains in Multi-Hop QA

“What was the father of Kasper Schmeichel voted to be by the IFFHS in 1992?”



“Were Scott Derrickson and Ed Wood of the same nationality?”



## What we want:

*A modular network dynamically constructed according to different question types.*

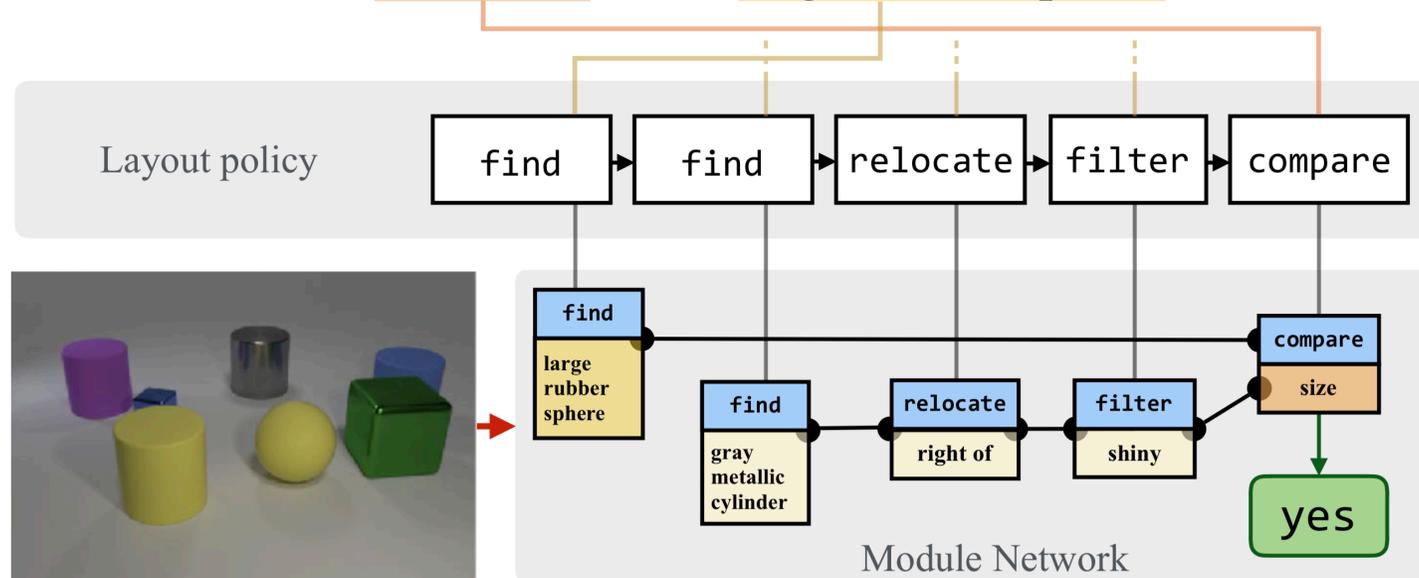
To achieve this, we need:

- A number of modules, each designed for a unique type of single-hop reasoning.
- A controller to
  - decompose the multi-hop question to multiple single-hop sub-questions,
  - design the network layout **based on the question** (decides which module to use for each sub-question).

# Neural Modular Networks

Neural Modular Network was originally proposed to solve Visual Question Answering (VQA), including VQA dataset and CLEVR dataset (Andreas et al. 2016, Hu et al. 2017).

There is a shiny object that is right of the gray metallic cylinder; does it have the same size as the large rubber sphere?



The original NMN controllers are usually trained with RL. Hu et al. (2018) proposed stack-based NMN w/ soft module execution to avoid indifferentiability in optimization

-Average over the outputs of all modules at every step instead of sample a single module at every step.

-Modules at different timestep communicate by popping/pushing the averaged attention output from/onto a stack.

- **Inputs:**
  - Question emb:  $u$
  - Decoding timestep:  $t$
- **Intermediate:**
  - Distribution over question words:  $cv_t$  (softly decompose the question)
- **Outputs:**
  - Module probability:  $p$  (Which module should be used at step  $t$ )
  - Sub-question vector:  $c_t$  (What sub-question to solve at step  $t$ )

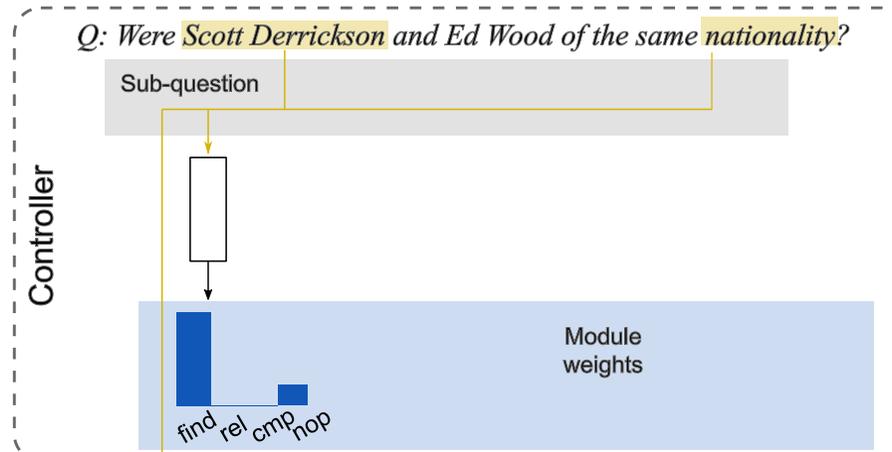
# Reasoning Modules

Inputs: Question emb:  $u$ , Sub-question vector:  $c_t$ , Context emb:  $h$

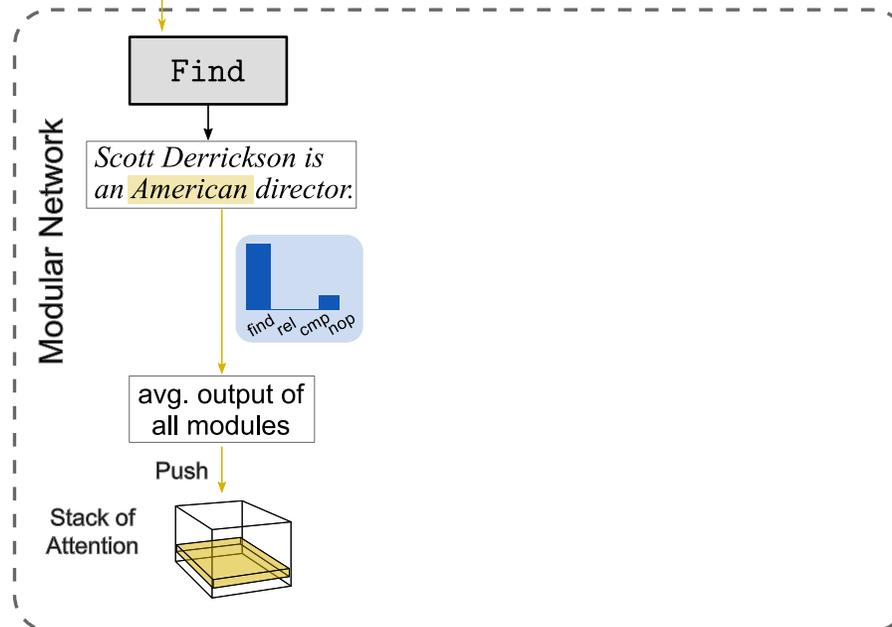
Module Name	Input Attention	Output Types	Implementation Details
<code>Find(u, c, h)</code>	(None)	Attention	$\text{BiAttn}(h \odot c_t, u)$
<code>Relocate(u, c, h)</code>	$a_1$	Attention	$\text{Find}(u, c_t, h \odot (a_1 \cdot h))$
<code>Compare(u, c, h)</code>	$a_1, a_2$	Yes/No	$\sigma(\text{MLP}([c_t, a_1 \cdot h, a_2 \cdot h, c_t \cdot (a_1 - a_2) \cdot h]))$
<code>NoOp(u, c, h)</code>	(None)	(None)	(None)

# Putting an NMN together...

Controller:

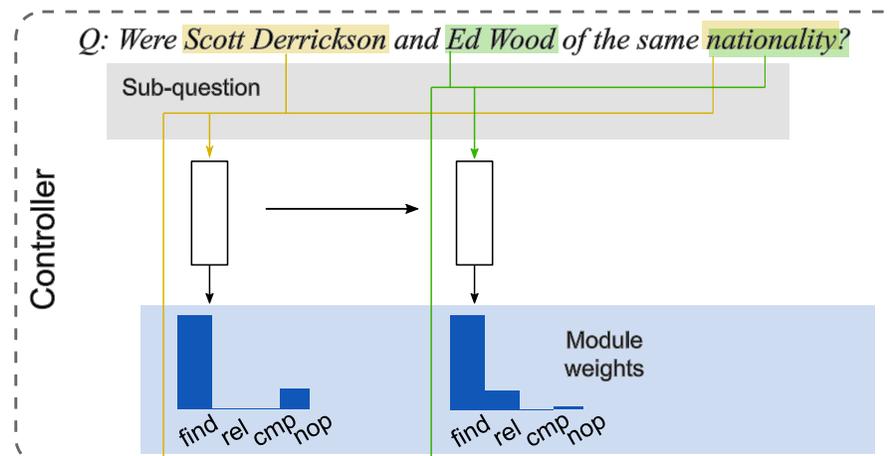


Modules:

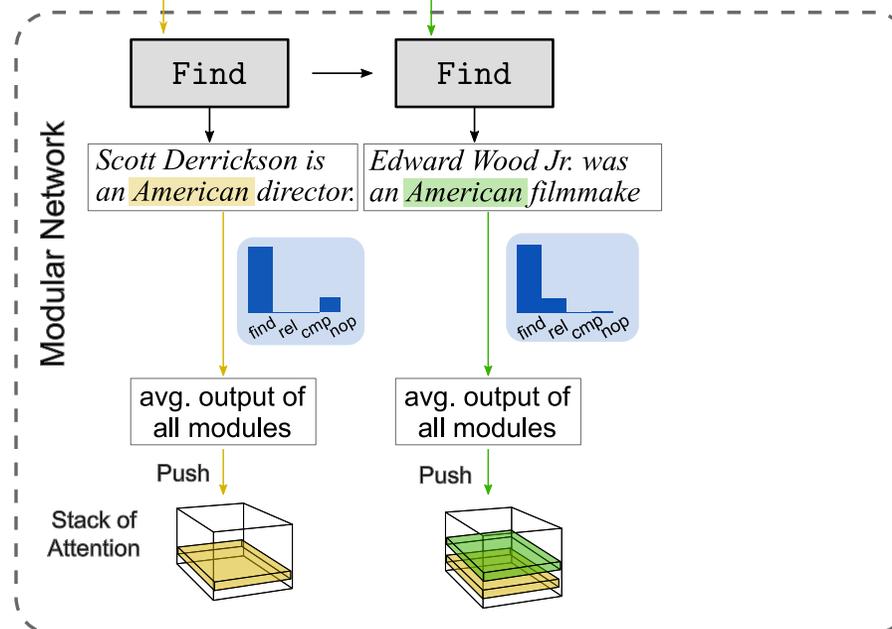


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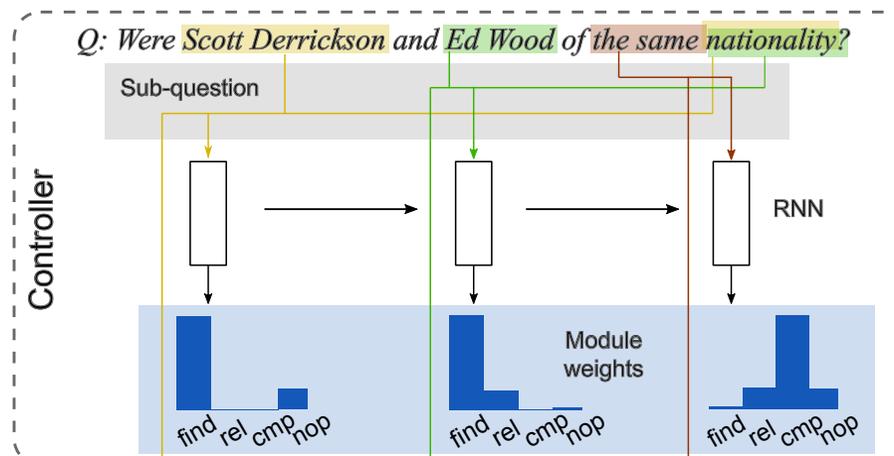


Modules:

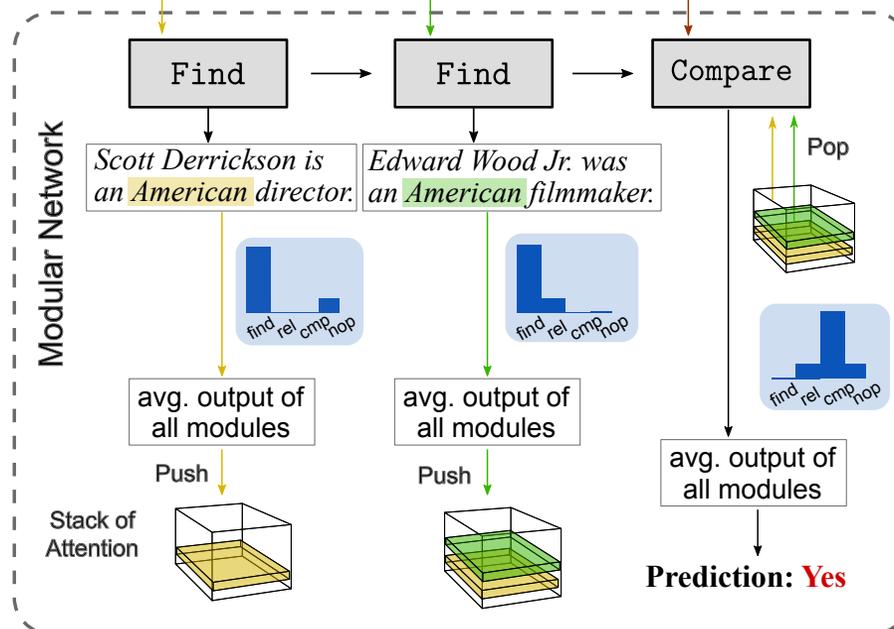


# Putting an NMN together...

Controller:



Modules:



# Main Results on HotpotQA

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	Dev	Test
	F1	F1
BiDAF Baseline	57.19	55.81
Original NMN	40.28	39.90
Our NMN	63.35	62.71

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# Ablation Studies

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	Bridge	Comparison
	F1	F1
<b>Our NMN</b>	64.49	57.20
-Relocate	60.13	58.10
-Compare	64.46	56.00

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\*All models are evaluated on our dev set.

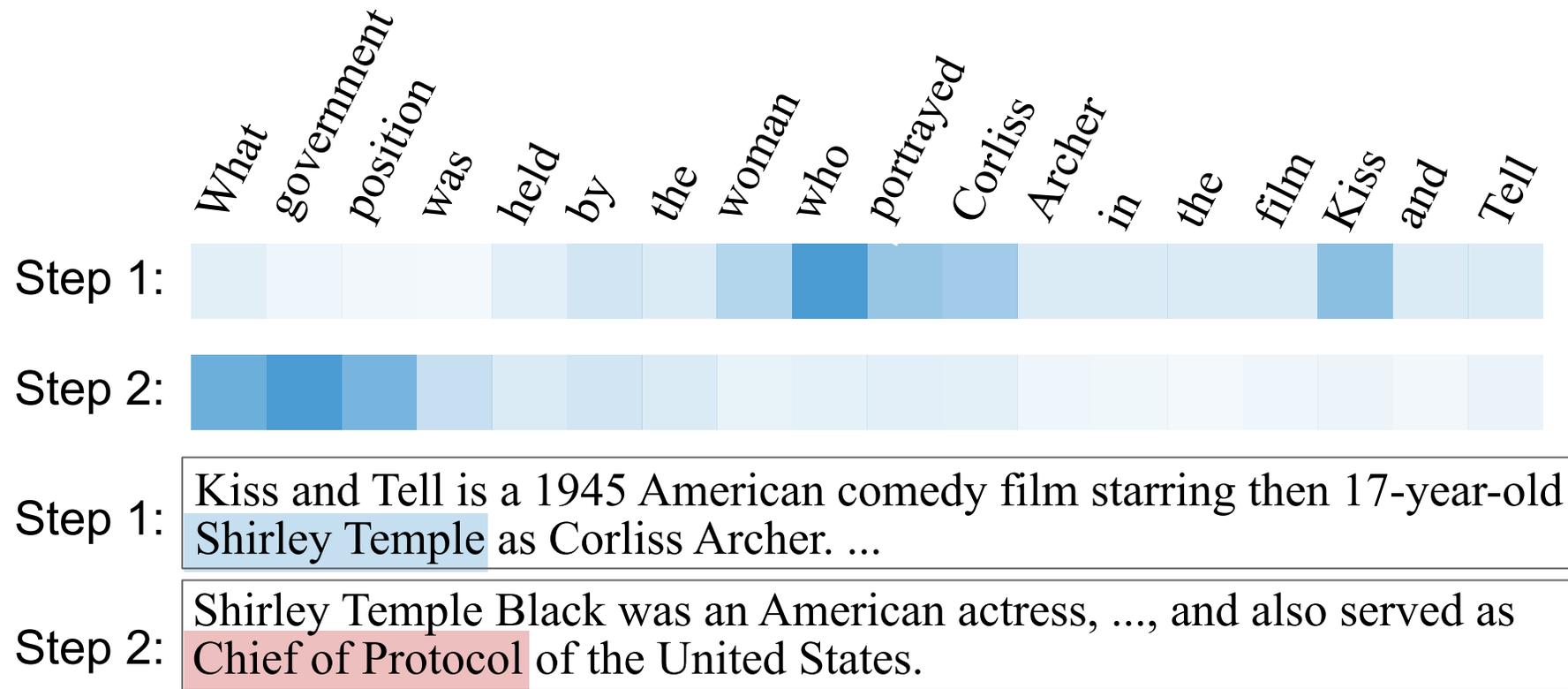
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Train	Reg	Reg	Adv	Adv
Eval	Reg	Adv	Reg	Adv
BiDAF Baseline	43.12	34.00	45.12	44.65
Our NMN	<b>50.13</b>	<b>44.70</b>	<b>49.33</b>	<b>49.25</b>

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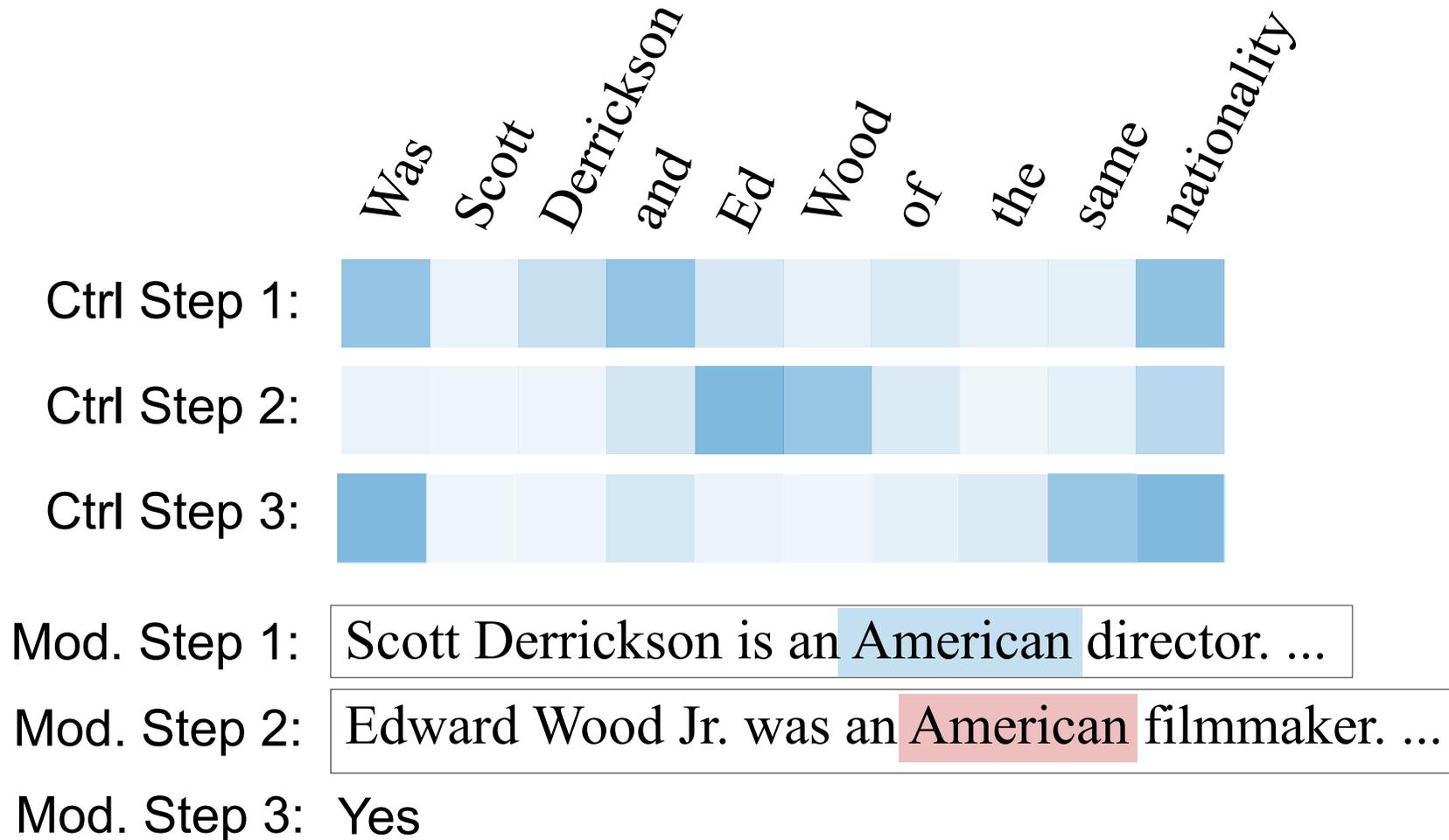
Table 4: EM scores after training on the regular data or on the adversarial data from [Jiang and Bansal \(2019\)](#), and evaluation on the regular dev set or the adv-dev set.

# Analysis: Controller Attention Visualization



- We also have initial human evaluation results on controller's sub-question soft decomposition/attention.

# Analysis: Controller Attention for Comparison Questions



# Analysis: Evaluating Module Layout Prediction

Bridge:

“What was the father of Kasper Schmeichel voted to be by the IFFHS in 1992?”

**Find -> Relocate: 99.9%**

Comparison  
Yes/No:

“Were Scott Derrickson and Ed Wood of the same nationality?”

**Find -> Find -> Compare:  
4.8 %**

**Find -> Relocate -> Compare:  
63.8%**

# Recent Results with BERT

- BERT+NMN achieves  $\geq$  results as Fine-tuned BERT-base (71.26 vs 70.66 F1).
- Module Layout Prediction results improved (compared to the non-BERT NMN):
- Hence, BERT+NMN model allows for stronger interpretability than non-modular BERT models (& non-BERT NMNs), but while maintaining BERT-style numbers.

Bridge-Type:

“What was the father of Kasper Schmeichel voted to be by the IFFHS in 1992?”

**Find -> Relocate: 99.9%**

Comparison  
Yes/No:

“Were Scott Derrickson and Ed Wood of the same nationality?”

**Find -> Find -> Compare:**  
~~4.8%~~ **96.9%**

**Find -> Relocate -> Compare:**  
~~63.8%~~ **0%**

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Bridge-Type:

“What was the father of Kasper Schmeichel voted to be by the IFFHS in 1992?”

**Find -> Relocate: 99.9%**

Comparison  
Yes/No:

“Were Scott D and Ed Wood of the same nationality?”

**Find -> Relocate -> Generate:**

Still several challenges/ long way to go, e.g., more complex MultihopQA datasets with more hops, more types of reasoning behaviors, etc.!

See Yichen’s full talk on Nov7 10.30am!

## (2) Divergent Reasoning Chains

[Welbl et al. 2018]

The *Polsterberg Pumphouse* ( German : Polsterberger Hubhaus ) is a pumping station above **the Dyke Ditch** in the **Upper Harz** in central Germany ...

**The Dyke Ditch** is the longest artificial ditch in the **Upper Harz** in central Germany.

The **Upper Harz** refers to ... the term Upper Harz covers the area of the seven historical mining towns ("Bergst\u00e4dte") - Clausthal, Zellerfeld, Andreasberg, Altenau, Lautenthal, Wildemann and Grund - in the present-day German federal state of **Lower Saxony**.

Query subject: *Polsterberg Pumphouse*

Query body: located\_in\_the\_administrative\_territorial\_entity

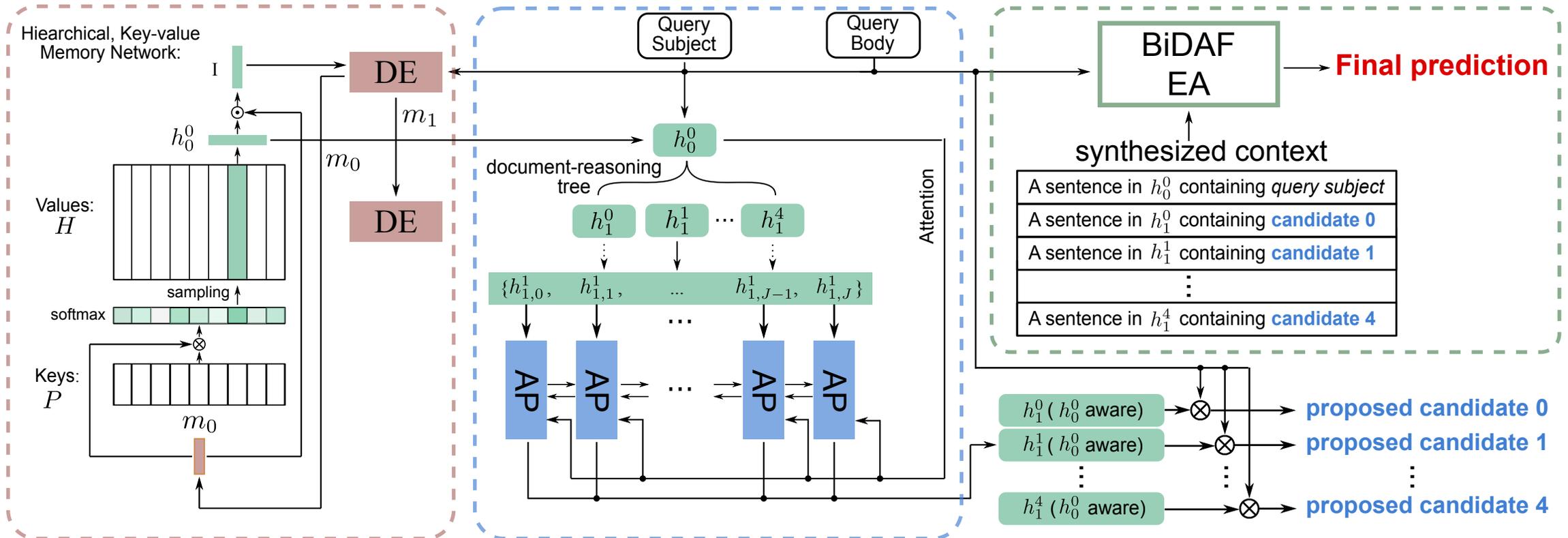
Answer: **Lower Saxony**



# Multi-Hop QA Requirements

- Success on Multi-Hop Reasoning QA requires a model to:
  - Locate a reasoning chain of important/relevant documents from a large pool of documents
  - Consider evidence loosely distributed in all documents from a reasoning chain to predict the answer
  - Weigh and merge evidence from **MULTIPLE** reasoning chains to predict the answer

# EPAr: Explore-Propose-Assemble reader



**Document Explorer (DE):**  
Iteratively selects relevant documents and represents multiple reasoning chains in a tree structure

**Answer Proposer (AP):**  
Proposes a candidate answer from every ancestor-aware root-to-leaf chain in the reasoning tree

**Evidence Assembler (EA):**  
Extracts key sentences from every reasoning chain and combines them to make a unified prediction

# Results - WikiHop and MedHop

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	Dev	Test
BiDAF Welbl et al., 2017*	-	42.9
Coref-GRU (Dhingra et al., 2018)	56.0	59.3
WEAVER (Raison et al., 2018)	64.1	65.3
MHQA-GRN (Song et al., 2018)	62.8	65.4
Entity-GCN (De Cao et al., 2018)	64.8	67.6
BAG (Cao et al., 2019)	66.5	69.0
CFC (Zhong et al., 2019)	66.4	70.6
EPAr (Ours)	<b>67.2</b>	69.1

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WikiHop

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	Test (Masked)	Test
FastQA (Weissenborn et al., 2017)	23.1	31.3
BiDAF (Seo et al., 2017)	33.7	47.8
CoAttention	-	58.1
Most Frequent Candidate	10.4	58.4
EPAr (Ours)	<b>41.6</b>	<b>60.3</b>

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MedHop

# Human Evaluation: Quality of Reasoning Tree

- Recall-k score is the % of examples where one of the human-annotated reasoning chains is recovered in the top-k root-to-leaf paths in the reasoning tree

	R@1	R@2	R@3	R@4	R@5
Random	11.2	17.3	27.6	40.8	50.0
1-hop TFIDF	32.7	48.0	56.1	63.3	70.4
2-hop TFIDF	42.9	56.1	70.4	78.6	82.7
DE	38.8	50.0	65.3	73.5	83.7
<b>TFIDF+DE</b>	<b>44.9</b>	<b>64.3</b>	<b>77.6</b>	<b>82.7</b>	<b>90.8</b>

- 2-hop TF-IDF performs much better than simple 1-hop TF-IDF retrieval
- DE without any TF-IDF retrieval pre-processing performs worse than 2-hop TF-IDF
- Combination of TF-IDF retrieval and DE performs better than each one of them alone

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DE					
TFIDF+DE					

Still several challenges/ long way to go, e.g., more complex MultihopQA datasets with more hops, longer and more #reasoning chains, etc.!

- 2-hop TF-IDF performs much better than simple 1-hop TF-IDF retrieval
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- Combination of TF-IDF retrieval and DE performs better than each one of them alone

# Adversarial Robustness



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Is *compositional reasoning* necessary to answer these multi-hop questions?

**Not always!**

# Reasoning Shortcut



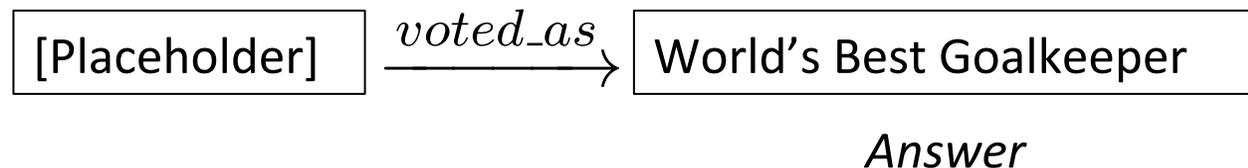
## Question

“What was the father of **Kasper Schmeichel** voted to be by the IFFHS in 1992?”

## Reasoning Chain:



## Reasoning Shortcut:



# Reasoning Shortcut



## Question

“What was the father of Kasper Schmeichel **voted to be by the IFFHS in 1992?**”

The answer can be directly inferred by word-matching the documents to maximum of the question !!!

## Context

Peter Bolesław Schmeichel is a Danish former professional footballer .., and was **voted** the **IFFHS** World's Best Goalkeeper **in 1992** and 1993.

Edson Arantes do Nascimento is a retired Brazilian professional footballer. In 1999, he was **voted** World Player of the Century by **IFFHS**. [Missing: **1992**]

Kasper Hvidt is a Danish retired handball goalkeeper, .. also **voted** as Goalkeeper of the Year March 20, 2009, [Missing: **1992, IFFHS**]



How to eliminate this reasoning shortcut from  
the data to **ENFORCE** compositional  
reasoning?

**Building adversarial documents  
as better distractors**

# Adversarial Document



## Question

“What was the father of Kasper Schmeichel **voted to be by the IFFHS in 1992?**”

## Context

Peter Bolesław Schmeichel is a Danish former professional footballer .., and was **voted the IFFHS World's Best Goalkeeper in 1992** and 1993.

## Adversarial Document

R. Kelly Schmeichel is a Danish former professional footballer .., and was **voted the IFFHS World's Best Defender in 1992** and 1993.

A model exploiting the reasoning shortcut will now find two plausible answers!



# BERT (Document Retrieval Results)



\* Exact-Match scores between 2 golden documents and 2 retrieved documents

Train \ Eval	Eval = Regular	Eval = Adv
Train = Regular	89.44	44.67
Train = Adv	89.03	80.14

- The performance of the BERT retrieval model trained on the regular training set **dropped** a lot when evaluated on the adversarial data.
- BERT is actually exploiting the reasoning shortcut instead of performing multi-hop reasoning.

# BERT (Document Retrieval Results)



\* Exact-Match scores between 2 golden documents and 2 retrieved documents

Train \ Eval	Eval = Regular	Eval = Adv
Train = Regular	89.44	44.67
Train = Adv	89.03	80.14

- After being trained on the adversarial data, BERT achieves significantly higher EM score in adversarial evaluation.
- Adversarial training is able to teach the model to be aware of distractors and force it not to take the reasoning shortcut, but there is still a remaining drop in performance.

# Bi-attention + Self-attention Baseline



\* Exact-Match scores

Train \ Eval	Eval = Regular	Eval = Adv
Train = Regular	43.12	34.00
Train = Adv	45.12	44.65

- The performance of the baseline trained on the regular training set **dropped** a lot when evaluated on the adversarial data.
- The model that performs well in the original data is actually exploiting the reasoning shortcut instead of performing multi-hop reasoning.

# Bi-attention + Self-attention Baseline



\* Exact-Match scores

Train \ Eval	Eval = Regular	Eval = Adv
Train = Regular	43.12	34.00
Train = Adv	45.12	44.65

- After being trained on the adversarial data, the baseline achieves significantly higher EM score in adversarial evaluation.
- Adversarial training is able to teach the model a bit to be aware of distractors and force it not to take the reasoning shortcut, but still big room for improvement.



- Manual Verification of Adversaries
  - 0 out of 50 examples had contradictory answers
- Model Error (Adversary Success) Analysis
  - In 96.3% of the failures, the model's prediction spans at least one of the adversarial documents
- Adversary Failure Analysis
  - Sometimes the reasoning shortcut still exists after adversarial documents are added
- **Next Steps/Questions:**
  - We might have made the model robust to one kind of attack but there might be others?
  - How do we ensure robustness to other adversaries we haven't thought of?

# Auto-Augment Adversary Generation



Ribeiro et al., 2018; Zhao et al., 2018

**How do we automatically generate the best adversaries without manual design?** Our AutoAugment model consists of a controller and a target model. The controller first samples a policy that transforms the original data to augmented data, on which the target model retrains. After training, the target model is evaluated to obtain the performance on the validation set. This performance is then fed back to the controller as the reward signal.

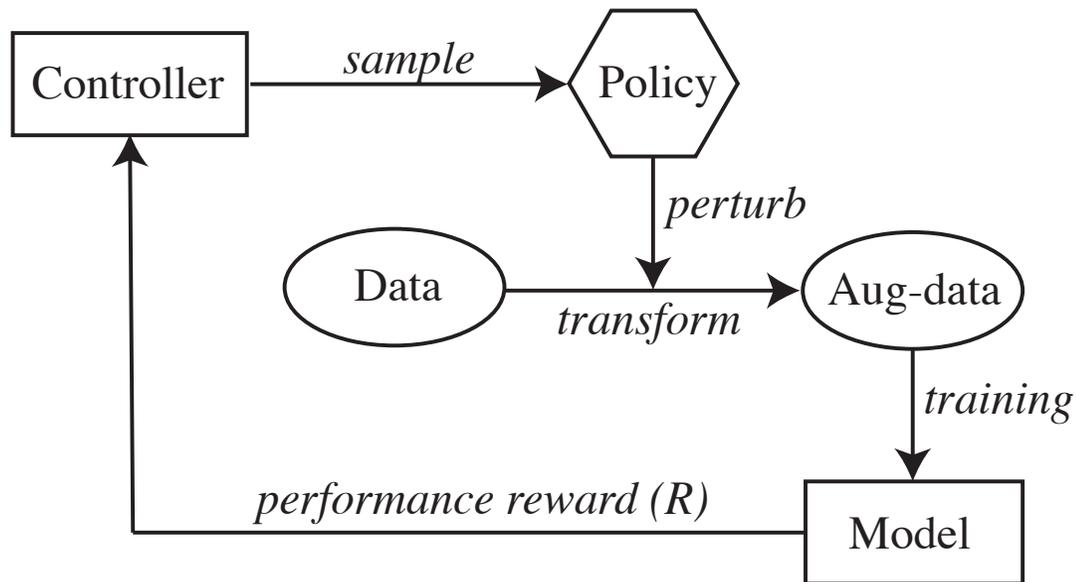


Figure 1: The controller samples a policy to perturb the training data. After training on the augmented inputs, the model feeds the performance back as reward.

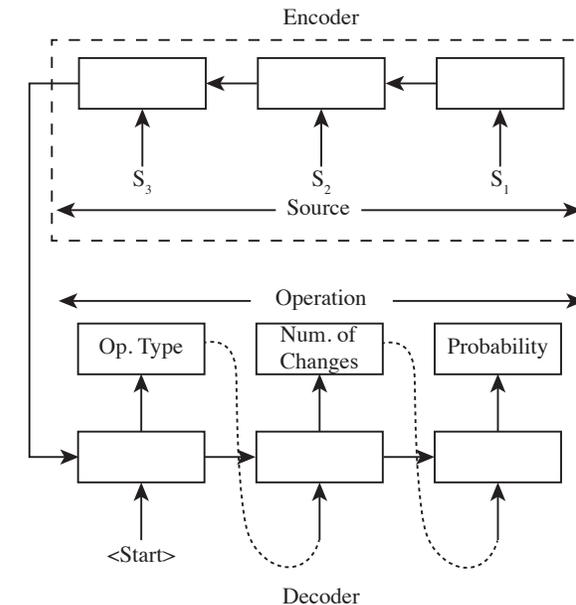


Figure 3: AutoAugment controller. An input-agnostic controller corresponds to the lower part of the figure. It samples a list of operations in sequence. An input-aware controller additionally has an encoder (upper part) that takes in the source inputs of the data.

# Auto-Augment Adversary Generation



## Policy Hierarchy and Search Space:

- A policy consists of 4 sub-policies;
- Each sub-policy consists of 2 operations applied in sequence;
- Each operation is defined by 3 parameters: **Operation Type**, **Number of Changes** (the maximum # of times allowed to perform operation, and **Probability** of applying that operation.
- Our pool of operations contains **Random Swap**, **Stopword Dropout**, **Paraphrase**, **Grammar Errors**, and **Stammer**.

## Subdivision of Operations:

- **Stopword Dropout:** To allow the controller to learn more nuanced combinations of operations, divide Stopword Dropout into 7 categories: Noun, Adposition, Pronoun, Adverb, Verb, Determiner, and Other.
- **Grammar Errors:** Noun (plural/singular confusion) and Verb (verb inflected/base form confusion).

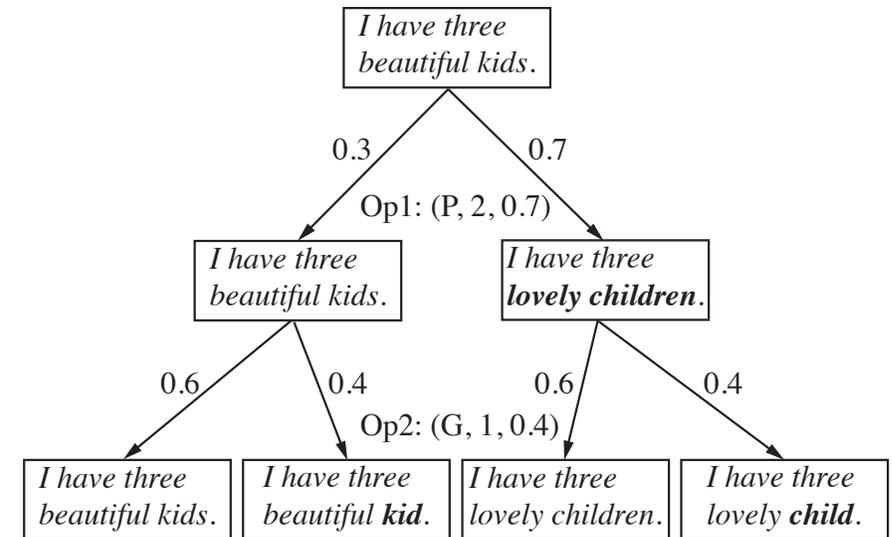


Figure 2: Example of a sub-policy applied to a source input. E.g., the first operation (Paraphrase, 2, 0.7) paraphrases the input twice with probability 0.7.

# Auto-Augment Adversary Generation



- **Setup:** Variational Hierarchical Encoder-Decoder (VHRED) (Serban et al., 2017b) on troubleshooting Ubuntu Dialogue task (Lowe et al., 2015); REINFORCE (Williams, 1992; Sutton et al., 2000) to train the controller.
- **Evaluation:** Serban et al. (2017a), evaluate on F1s for both activities (technical verbs) and entities (technical nouns). We also conducted human studies on Mturk, comparing each of the input-agnostic/aware models with the VHRED baseline and All-operations from Niu and Bansal (2018).

	Activity F1	Entity F1
LSTM	1.18	0.87
HRED	4.34	2.22
VHRED	4.63	2.53
VHRED (w/ attn.)	5.94	3.52
All-operations	6.53	3.79
Input-aware	<b>7.04</b>	3.90
Input-agnostic	7.02	<b>4.00</b>

Table 1: Activity, Entity F1 results reported by previous work, the All-operations and AutoAugment models.

	W	T	L	W - L
Input-agnostic vs. baseline	48	23	29	19
Input-aware vs. baseline	45	27	28	17
Input-agnostic vs. All-ops	43	27	30	13
Input-aware vs. All-ops	50	13	37	13

Table 4: Top 3 policies on the validation set and their test performances. Operations: R=Random Swap, D=Stopword Dropout, P=Paraphrase, G=Grammar Errors, S=Stammer. Universal tags: n=noun, v=verb, p=pronoun, adv=adverb, adp=adposition.

Sub-policy1	Sub-policy2	Sub-policy3	Sub-policy4
P, 1, 0.5	D <sub>v</sub> , 3, 0.2	R, 3, 0.9	D <sub>p</sub> , 2, 0.3
D <sub>adv</sub> , 4, 0.4	R, 1, 0.5	D <sub>adp</sub> , 1, 0.5	D <sub>adp</sub> , 2, 0.1
D <sub>n</sub> , 1, 0.8	D <sub>o</sub> , 3, 1.0	P, 4, 0.4	G <sub>n</sub> , 3, 0.3
G <sub>v</sub> , 1, 0.9	D <sub>o</sub> , 3, 0.1	S, 3, 0.4	R, 1, 0.2
D <sub>v</sub> , 2, 0.5	D <sub>v</sub> , 2, 0.7	S, 3, 0.5	P, 1, 1.0
R, 2, 0.2	G <sub>v</sub> , 1, 0.9	D <sub>o</sub> , 1, 0.5	G <sub>n</sub> , 2, 0.6

Table 2: Human evaluation results on comparisons among the baseline, All-operations, and the two AutoAugment models. W: Win, T: Tie, L: Loss.



# Auto-Augment Adversary Generation

- **Setup:** Variational Hierarchical Encoder-Decoder (VHRED) (Serban et al., 2017b) on troubleshooting Ubuntu Dialogue task (Lowe et al., 2015); REINFORCE (Williams, 1992; Sutton et al., 2000) to train the controller.
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			7	13

performances. Operations: Grammar Errors, =adverb, adp=adposition.

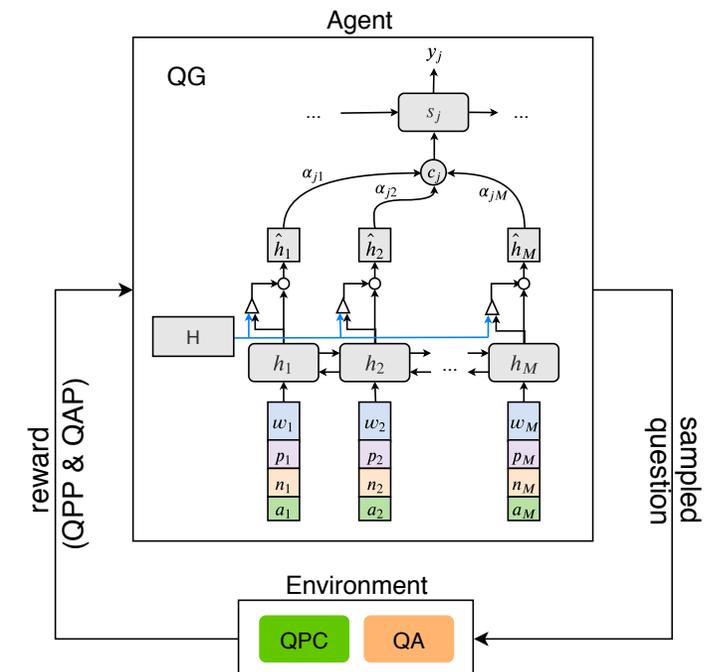
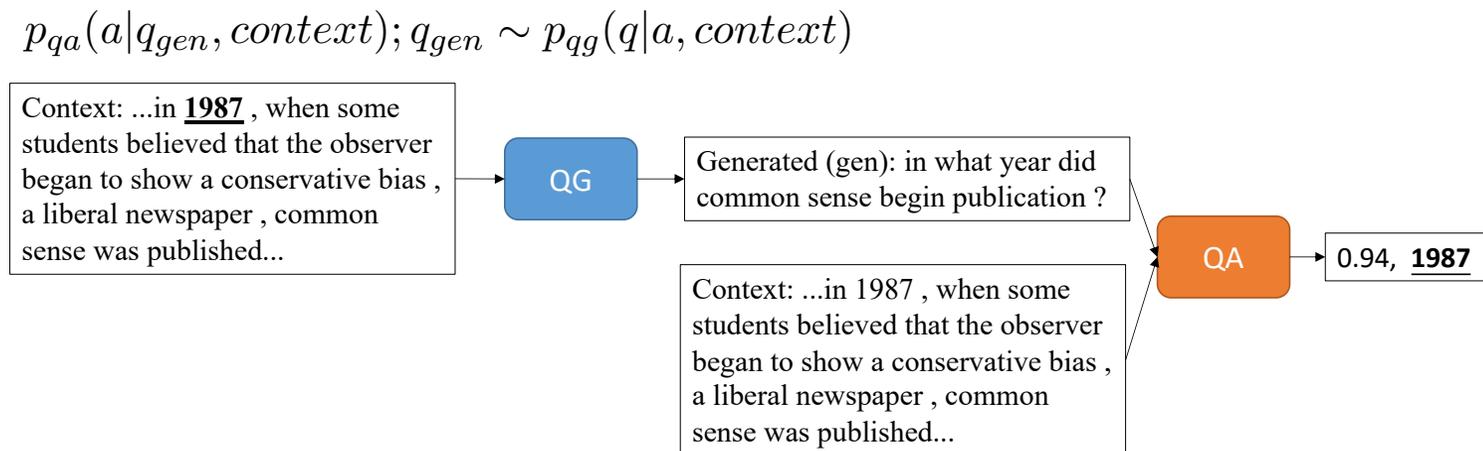
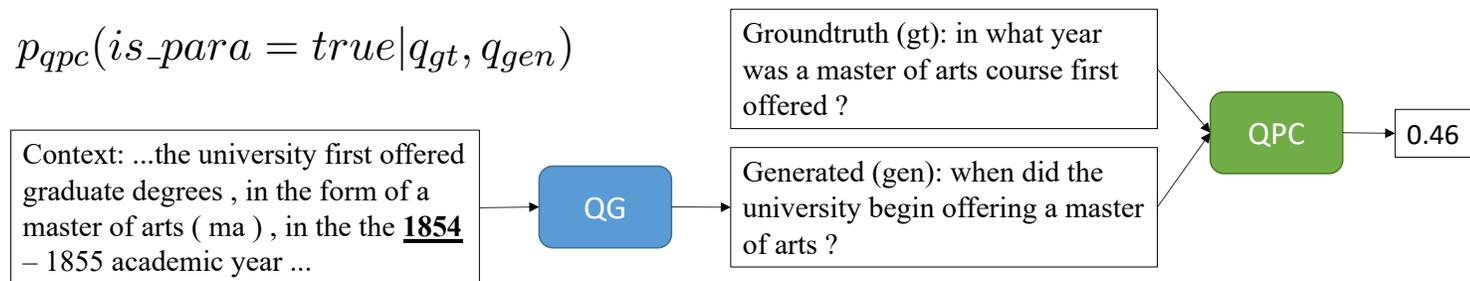
Still several challenges: better AutoAugm algorithms for RL speed, reward sparsity, other NLU/NLG tasks? Visit Tong's poster Nov5 3.30pm for more details!

$D_{adv}, 4, 0.4$	$R, 1, 0.5$	$D_{adp}, 1, 0.5$	$D_{adp}, 2, 0.1$
$D_n, 1, 0.8$	$D_o, 3, 1.0$	$P, 4, 0.4$	$G_n, 3, 0.3$
$G_v, 1, 0.9$	$D_o, 3, 0.1$	$S, 3, 0.4$	$R, 1, 0.2$
$D_v, 2, 0.5$	$D_v, 2, 0.7$	$S, 3, 0.5$	$P, 1, 1.0$
$R, 2, 0.2$	$G_v, 1, 0.9$	$D_o, 1, 0.5$	$G_n, 2, 0.6$

Table 2: Human evaluation results on comparisons among the baseline, All-operations, and the two AutoAugment models. W: Win, T: Tie, L: Loss.

# Robustness to New Questions via Semi-Supervised QG-for-QA

- Can also address Auto-Augment Robustness for QA by making it robust to new types of questions it has not seen before (via automatic question generation)!
- **Semantics-reinforced QG:** We first improve QG by addressing a “semantic drift” problem with two semantics-enhanced rewards (QPP = Question Paraphrasing Probability & QAP = Question Answering Probability) and introduce a QA-based QG evaluation method.

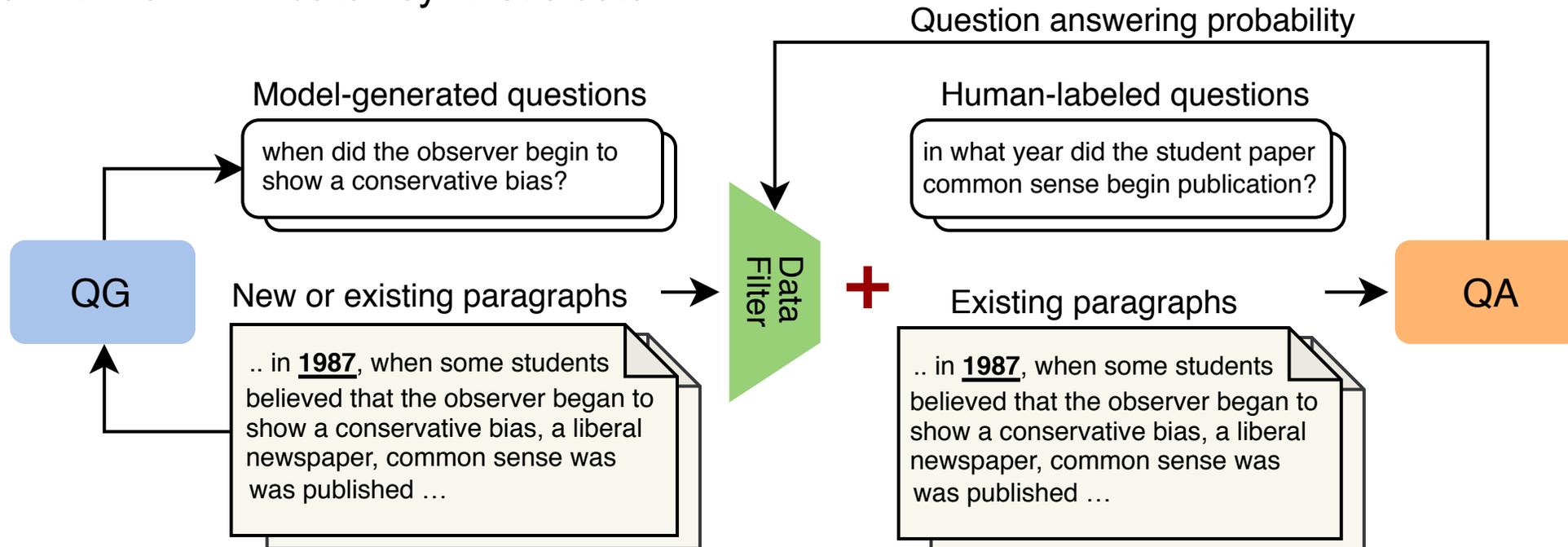


# Semi-Supervised QA with QG-Augmentation



Augment QA dataset with QG-generated examples (Generate from Existing Articles, and Generate from New Articles)

- (1) QAP filter: To filter out poorly-generated examples; Filter synthetic examples with  $QAP < \epsilon$ .
- (2) Mixing mini-batch training: To make sure that the gradients from ground-truth data are not overwhelmed by synthetic data, for each mini-batch, we combine half mini-batch ground-truth data with half mini-batch synthetic data.

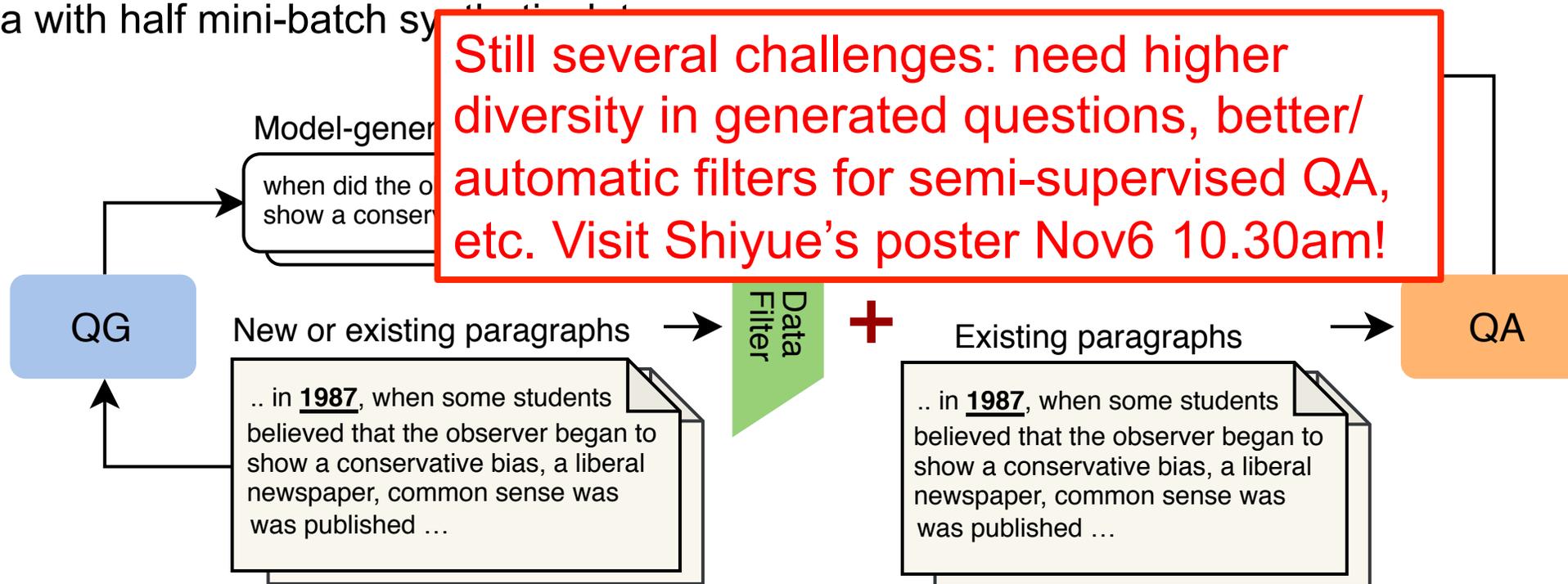


# Semi-Supervised QA with QG-Augmentation



Augment QA dataset with QG-generated examples (Generate from Existing Articles, and Generate from New Articles)

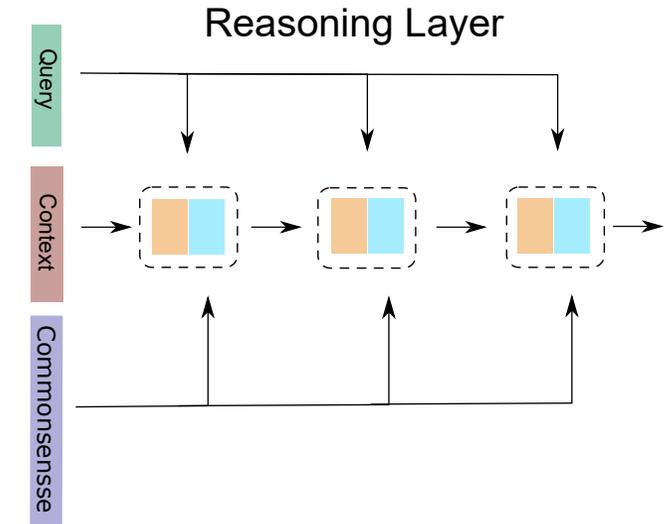
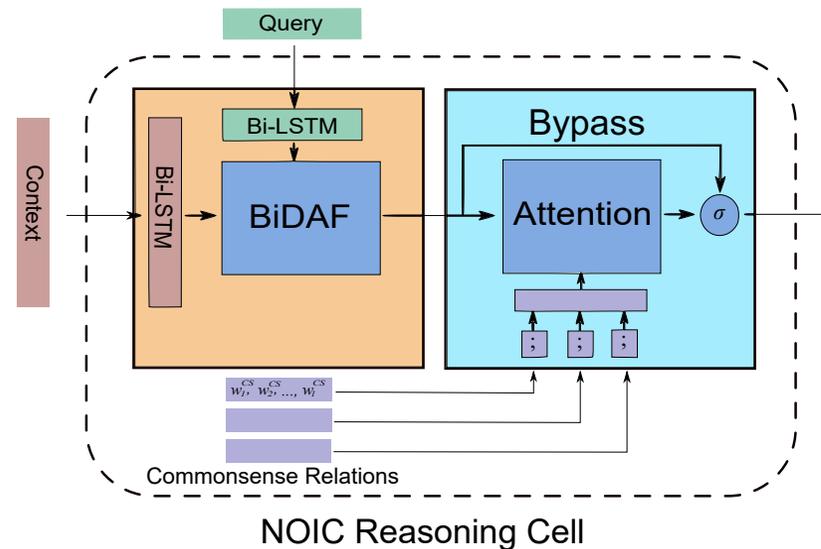
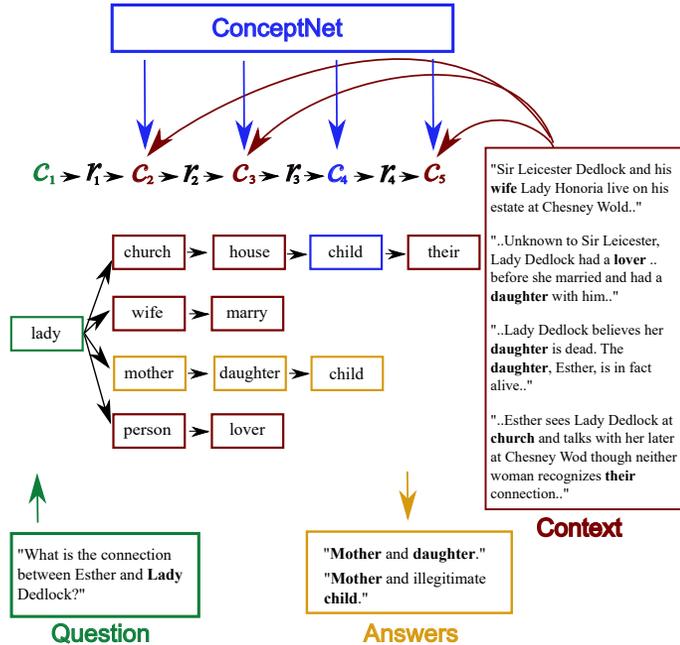
- (1) QAP filter: To filter out poorly-generated examples; Filter synthetic examples with  $QAP < \epsilon$ .
- (2) Mixing mini-batch training: To make sure that the gradients from ground-truth data are not overwhelmed by synthetic data, for each mini-batch, we combine half mini-batch ground-truth data with half mini-batch synthetic data.



# Commonsense/Missing Knowledge Robustness in QA



- We use 'bypass-attention' mechanism to reason jointly on both internal context and external commonsense, and essentially learn when to fill 'gaps' of reasoning and with what information



# Thoughts/Challenges/Current+Future Work

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- BERT vs modularity?
- Evaluating NMN's interpretability when using contextualized input embeddings (BERT).
- New reasoning behaviors in more complex tasks?
- Structured knowledge as commonsense for QA and other NLU/NLG tasks
- Ongoing: Question generation for Multihop QA
- Ongoing: Auto-Augment for MultihopQA and addressing RL slowness, reward sparsity, etc.
- Ongoing: Multilingual extensions of QA/MultihopQA
- Our Multimodal QA work: TVQA and TVQA+

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# Thank you!

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